

Scalable Training of Trustworthy and Energy-Efficient Predictive Graph Foundation Models for Atomistic Materials Modeling: A Case Study with HydraGNN

Massimiliano (Max) Lupo-Pasini

Oak Ridge National Laboratory

March 19, 2025

SOS27 Workshop, Engelberg, Switzerland



ORNL is managed by UT-Battelle LLC for the US Department of Energy

Team



Jong Youl Choi



Pei Zhang



Kshitij Mehta



David Rogers



Khaled Ibrahim Lawrence Berkeley National Laboratory



Karl W. Schulz AMD Research



Ashwin Aji AMD Research



Jorda Polo AMD Research



Prasanna Balaprakash



Driving motivation

Design new materials with desired properties and functionalities from atomistic structures

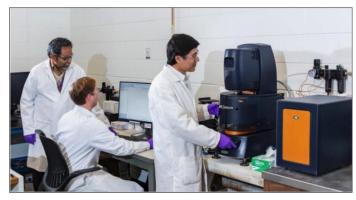
Multiple applications:

- refractory high entropy alloys for fusion
- organic molecules with desired optoelectronic properties
- drug design
- energy innovation (batteries, superconductors, etc.)
- manufacturing

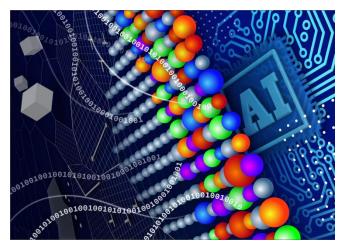
ORNL is the ideal environment to carry out this program due to its

- mission driven research portfolio
- unique facilities and recognized staff expertise
- access to scientific data
- collaborative environment

Current AI/ML approaches support the applications above, but require large amount of domain-specific training data.



Picture from https://www.printedelectronicsnow.com/contents/view_breaking-news/2018-12-24/ornl-new-composite-advances-lignin-as-renewable-3d-printing-material/



Picture from https://www.mpg.de/20096180/artificial-intelligence-in-material-design



Graph foundation models (GFMs)

In contrast, foundation models (FMs) are trained only once on generic data.

Once trained, FMs are fine-tuned on a wide variety of downstream tasks, with much less task-specific data.

Why GFMs?

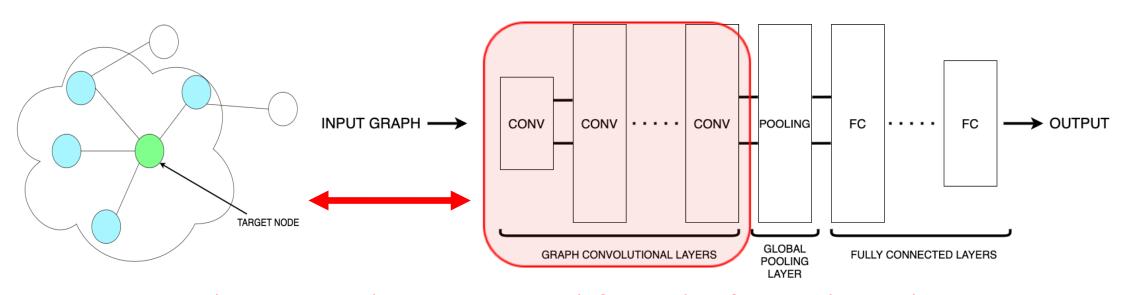
- Large Language Models (LLMs), originally developed for text applications, do not capture many aspects of materials' structure
- The atomistic structure maps naturally onto the graph structure of the model
- This facilitates developing physics-informed AI/ML methods
- Graph neural networks (GNN) are the backbone of GFM architectures



Graph neural networks (GNNs)

The architecture of a GNN consists of:

- a graph embedding layer
- 2. hidden graph layers to capture short range interactions between nodes in the graph
- 3. pooling layers interleaved with graph layers to synthetize information related to adjacent nodes via aggregation
- 4. fully connected (FC) dense layers at the end of the architecture to capture global features of the properties of interest



Convolutional operations aggregate information from neighboring nodes, thereby enabling transferability of local information to larger scales

HydraGNN: a scalable GNN architecture for materials science applications

https://www.osti.gov/doecode/biblio/65891

https://github.com/ORNL/HydraGNN

Multi-task learning (MTL) from multiple source, heterogeneous, imbalanced data

Equivariance for efficient data processing and computational savings

Distributed data parallelism



HydraGNN: (i) supports continuing upgraded software; (ii) supports diverse scientific applications; and (iii) is portable across heterogeneous computing environments

Predicts simultaneously multiple quantities of interest

Stabilizes training avoids ill-conditioning and overfitting

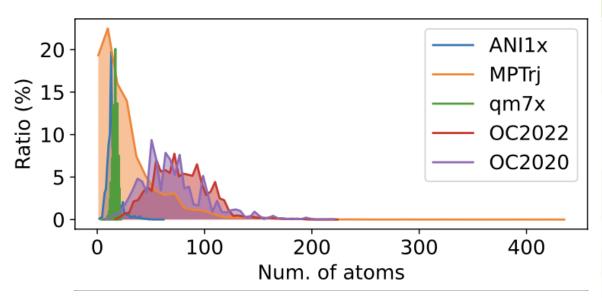
Efficient scaling

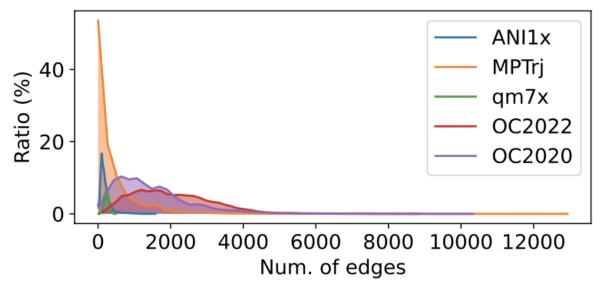
Ensures transferability



Pre-training of GFMs using HydraGNN

Aggregation of large volumes of open-source datasets





Dataset	Type of compounds	# data samples
Open Catalyst 2020	Alloy slabs with interacting catalysts on the surface	134,929,018
Open Catalyst 2022	Alloy slabs with interacting catalysts on the surface	8,847,031
Materials Project Trajectory	Bulk metals and alloys	1,580,395
ANI1x	Organic molecules	4,956,005
QM7x	Organic molecules	4,195,237
Total		154,507,686

<u>1e8</u>

ک Frequency

1

	Periodic Table Heatmap of Element Frequencies																
1 H											2 He						
3	4	5 6 7 8 9									10						
Li	Be	B C N O F									Ne						
11	12									18							
Na	Mg									Ar							
19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36
K	Ca	Sc	Ti	V	Cr	Mn	Fe	Co	Ni	Cu	Zn	Ga	Ge	As	Se	Br	Kr
37	38	39	40	41	42	43	44	45	46	47	48	49	50	51	52	53	54
Rb	Sr	Y	Zr	Nb	Mo	Tc	Ru	Rh	Pd	Ag	Cd	In	Sn	Sb	Te		Xe
55	56	57	72	73	74	75	76	77	78	79	80	81	82	83	84	85	86
Cs	Ba	La	Hf	Ta	W	Re	Os	Ir	Pt	Au	Hg	Tl	Pb	Bi	Po	At	Rn
87	88	89	104	105	106	107	108	109	110	111	112	113	114	115	116	117	118
Fr	Ra	Ac	Rf	Db	Sg	Bh	Hs	Mt	Ds	Rg	Cn	Nh	Fl	Mc	Lv	Ts	Og
		58 Ce	59 Pr	60 Nd	61 Pm	62 Sm	63 Eu	64 Gd	65 Tb	66 Dy	67 Ho	68 Er	69 Tm	70 Yb	71 Lu		
		90 Th	91 Pa	92 U	93 Np	94 Pu	95 Am	96 Cm	97 Bk	98 Cf	99 Es	100 Fm	101 Md	102 No	103 Lr		

Data cleaning

Dataset	Number of data samples removed
ANI1x [67]	0
QM7-X [68]	0
OC2020 [43]	1
OC2022 [44]	12,270
MPTrj [41]	151
Total	12,421

We removed data-samples with L2-norm of the force-tensor above 100 eV/angstrom



Data alignment

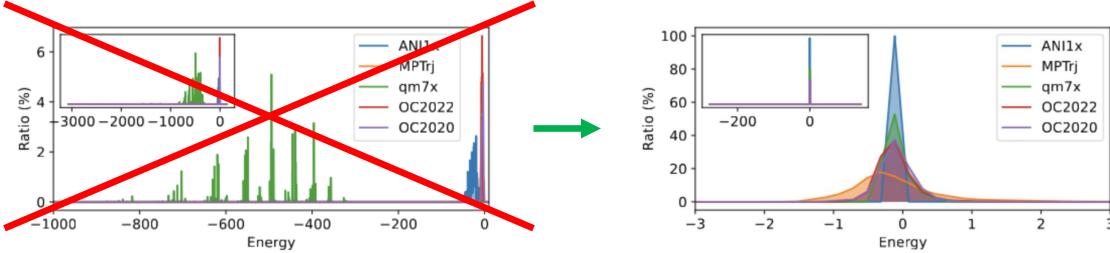
We **re-aligned** multi-source multi-fidelity data to transform the energy of each atomistic structure during pre-processing by subtracting a linear regression term. For each dataset, the linear regression term was calculated by solving the following least-squares problem:

$$\underset{C_1, \dots, C_{118}}{\operatorname{arg\,min}} \sum_{i=1}^{N_{data}} \left(e_0^i - \sum_{Z=1}^{118} C_Z n_Z^i \right)^2$$

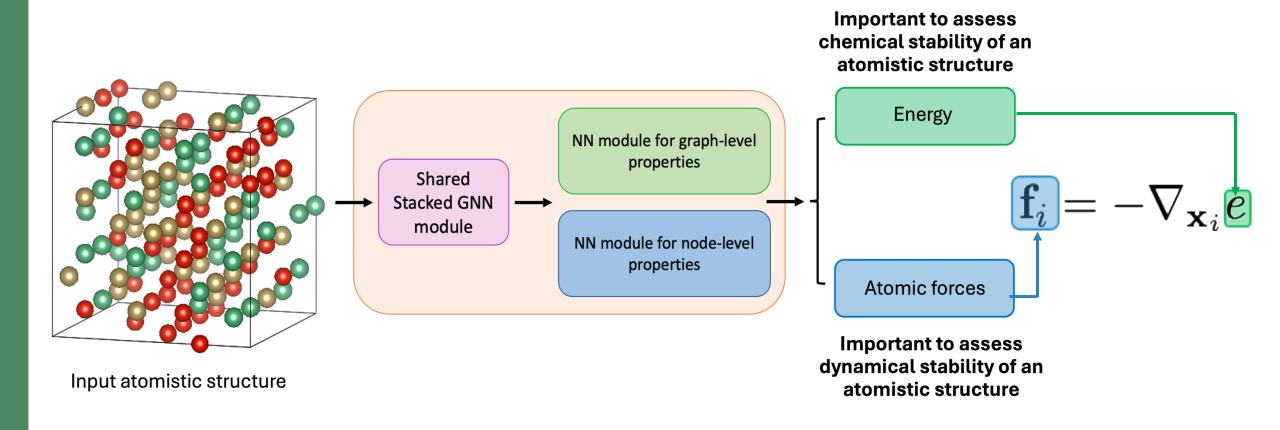
 e_0^i = reference energy for the atomistic structure i

 n_Z^i = number of atoms for element number **Z** for belonging to the atomistic structure i

 C_Z = regression coefficients that needs to be computed



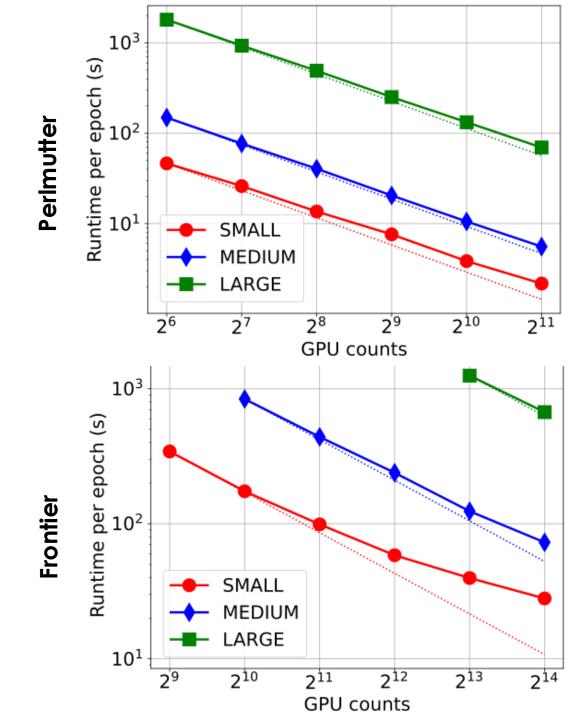
Multi-tasking HydraGNN architecture



Strong scaling performance

Model size	SMALL	MEDIUM	LARGE
Type of MPNN layer	EGNN	EGNN	EGNN
# MPNN layers	3	6	6
# neurons in MPNN layers	50	500	2,000
# FC layers	2	2	3
# neurons in FC layers	50	1,000	1,000
Number of parameters	58,404	14,539,004	163,129,004

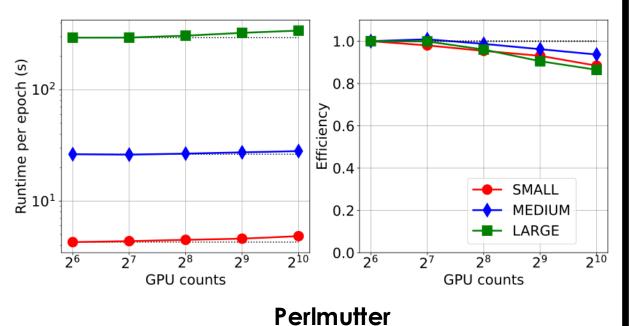
Top: GNN model sizes used for strong scaling tests on NERSC-Perlmutter and OLCF-Frontier.



Weak scaling performance

Model size	SMALL	MEDIUM	LARGE
Type of MPNN layer	EGNN	EGNN	EGNN
# MPNN layers	3	6	6
# neurons in MPNN layers	50	500	2,000
# FC layers	2	2	3
# neurons in FC layers	50	1,000	1,000
Number of parameters	58,404	14,539,004	163,129,004

Top: GNN model sizes used for strong scaling and weak scaling tests on NERSC-Perlmutter and OLCF-Frontier.



(s) 10² 0.8 Efficiency 0 0 0 Runtime per 0.4 **SMALL MEDIUM** 0.2 10^{1} LARGE 0.0 28 210 211 210 29 211 **GPU** count **GPU** count **Frontier**

OAK RIDGE
National Laboratory

Hyperparameter optimization (HPO)

Challenges:

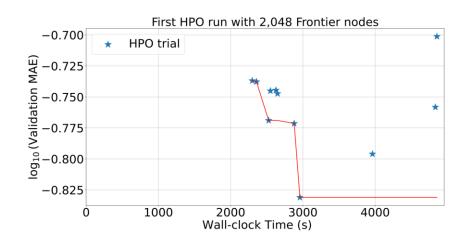
- The hyperparameter space is high-dimensional, thus making its exploration combinatorically complex
- The GFM training for each HPO trial needs to scale on 128 Frontier nodes to effectively process large volumes of data using DDP
- → Need for massive computational resources (and energy)

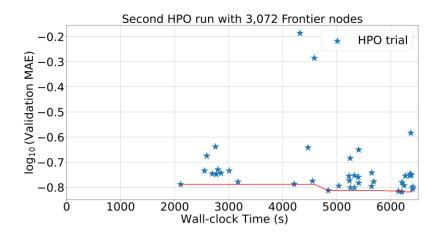
Proposed approach:

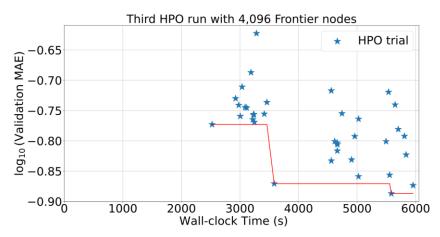
- Progressively ramp-up the scale of HPO with a funneling approach, whereby preliminary HPO runs at smaller scale instructing successive HPO runs at larger scale
- Select GFMs with optimal balance between accuracy vs. energy-savings
- Complete training till convergence is reached only for selected GFMs

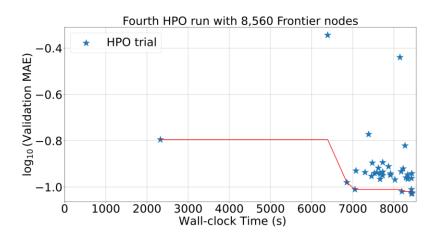


HPO runs with increasing scale up to 8,560 Frontier nodes









Progressive decrease of the validation loss function through consecutive HPO runs



'Omnistat' for collection of key telemetry from AMD GPUs

Github repository: https://github.com/AMDResearch/omnistat

Omnistat provides a set of utilities to aggregate scale-out system metrics via low-overhead sampling across all hosts in a cluster or, alternatively on a subset of hosts associated with a specific user job.

Relevant target metrics include:

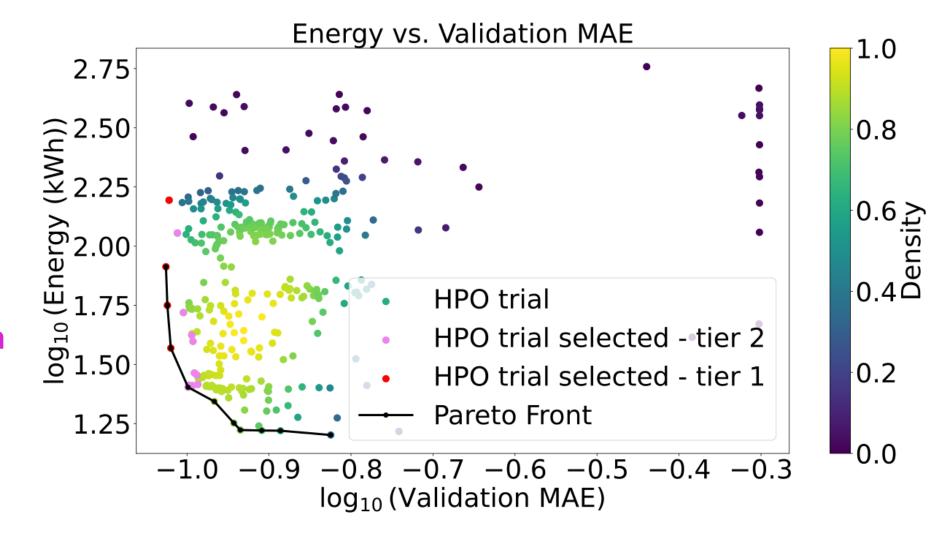
- GPU utilization (occupancy)
- High-bandwidth memory (HBM) usage
- GPU power
- GPU temperature
- GPU clock frequency (Mhz)
- GPU memory clock frequency (Mhz)
- GPU throttling events



Selection of HPO trials with optimal trade-off between accuracy and energy-savings

Tier 1: 4 GFMs with clear advantage in accuracy

Tier 2: 11 GFMs with best trade-off between accuracy and energy savings

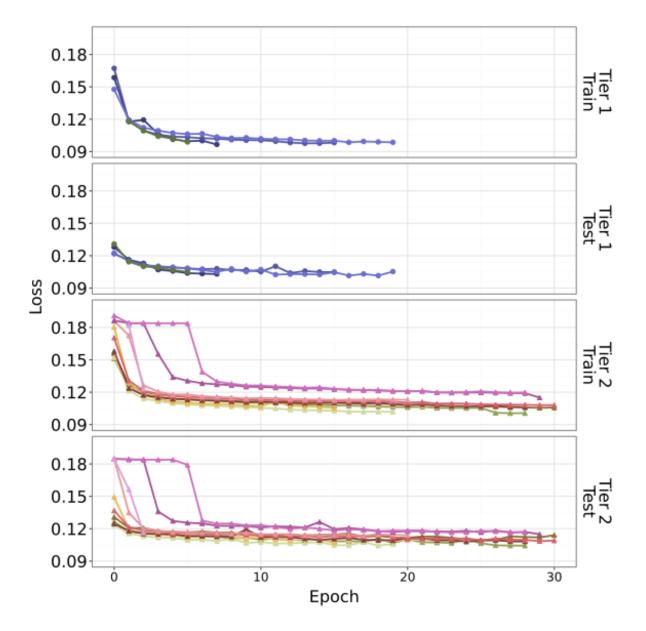


Full training of selected HPO trials

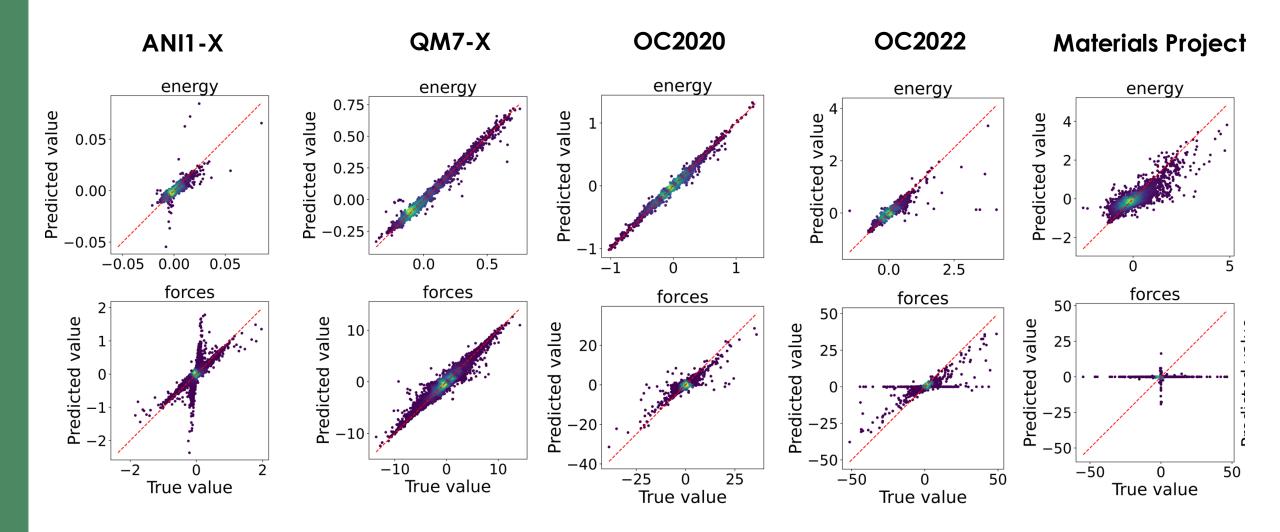
Best HPO trials are trained till convergence using checkpoint restart strategies to facilitate resubmission of job on OLCF-Frontier.

Early stopping is applied to force interruption when validation loss function does not significantly improve across 10 consecutive epochs.

Training of each GFM took approximately 10 wall-clock hours using 128 nodes for DDP



Ensemble learning performance



Publication and release of GFM parameters with examples

Publication:

M. Lupo Pasini, J. Y. Choi, K. Mehta, P. Zhang, D. Rogers, J. Bae, K. Ibrahim, A. Aji, K. W. Schulz, J. Polo, and P. Balaprakas. Scalable training of trustworthy and energy-efficient predictive graph foundation models for atomistic materials modeling: a case study with HydraGNN.

J Supercomput 81, 618 (2025). https://doi.org/10.1007/s11227-025-07029-9

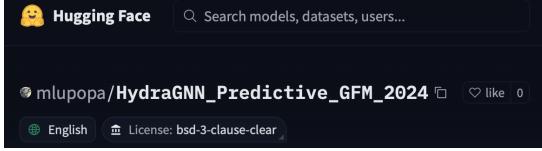
Models and pre-processed datasets released on OSTI.GOV:

M. Lupo Pasini, J. Y. Choi, K. Mehta, P. Zhang, D. Rogers, J. Bae, K. Ibrahim, A. Aji, K. W. Schulz, J. Polo, and P. Balaprakash (2024). HydraGNN_Predictive_GFM_2024 - Ensemble of predictive graph foundation models for ground state atomistic materials modeling. https://doi.org/10.13139/OLCF/2474799

Models with example scripts to load them available on Hugging Face:

https://huggingface.co/mlupopa/HydraGNN_Predictive_GFM_2024

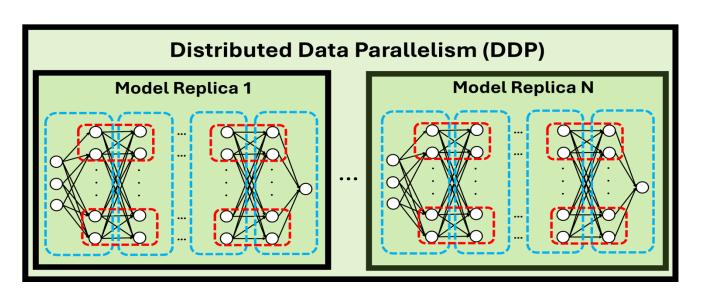


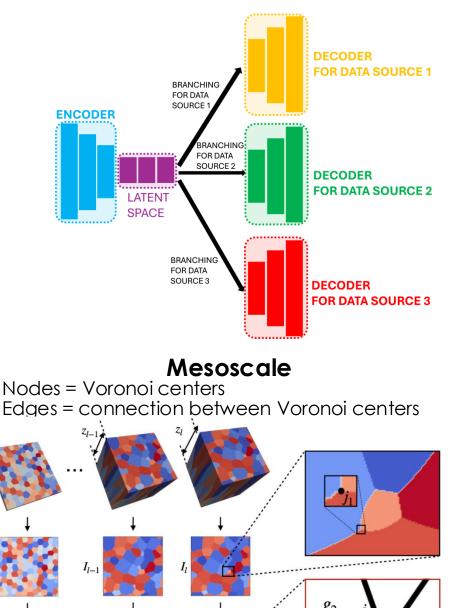




On-going and future work

- Integrate DDP, model parallelism (MP)
- Generalize MTL for stable and energy-efficient training
- Develop equivariant generative diffusion models with masking techniques
- Apply HydraGNN to modeling evolution of grain structure at mesoscopic scale







Acknowledgments

This research is partially supported by:

- The Artificial Intelligence Initiative as part of the Laboratory Directed Research and Development (LDRD) Program of Oak Ridge National Laboratory, managed by UT-Battelle, LLC, for the US Department of Energy under contract DE-AC05-00OR22725.
- The SciDAC Institute for Computer Science, Data, and Artificial Intelligence (RAPIDS), Lawrence Berkeley National Laboratory, which is operated by the University of California for the U.S. Department of Energy under contract DE-AC02-05CH11231.
- The US-DOE Advanced Scientific Computing Research (ASCR) under contract DE-SC0023490.

This research used resources of the Oak Ridge Leadership Computing Facility and of the Edge Computing program at the Oak Ridge National Laboratory. Computer time was provided by the INCITE program using the OLCF award CPH161 (AY2024), and OLCF Director's Discretion Project program using the OLCF awards MAT250 (AY2022) and LRN026 (AY2023).

This research also used resources of the National Energy Research Scientific Computing Center (NERSC), which is supported by the Office of Science of the U.S. Department of Energy under Contract No. DE-AC05-00OR22725 and No. DE-AC02-05CH11231, using NERSC awards ASCR-ERCAP0022058 (AY2022), ASCR-ERCAP0025216 (AY2023) and ASCR-ERCAP0027259 (AY2024).





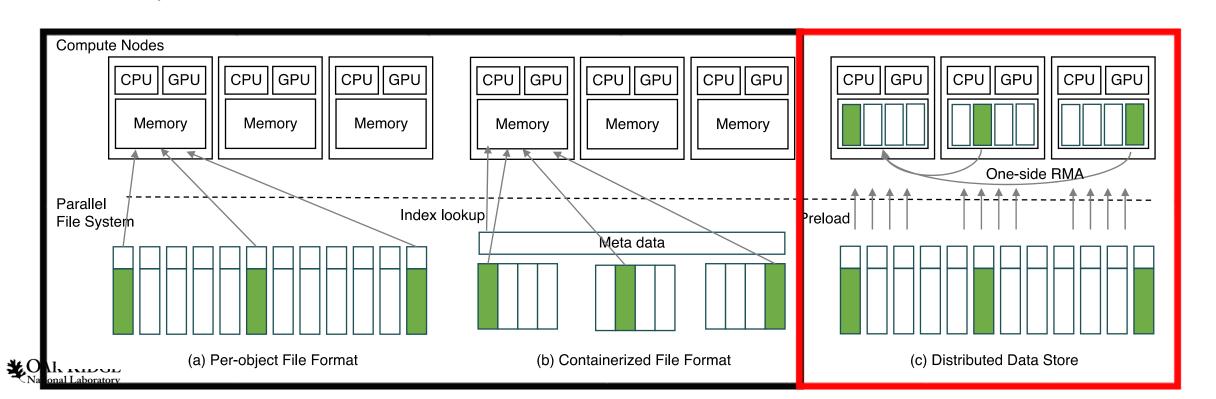
HydraGNN: scalable training with distributed data parallelism (DDP)

Traditional form of DDP:

- Move all data onto the memory of one compute unit
- Periodically pull data from the parallel file system (PFS

Distributed Data Store (DDStore) library partitions data in chunks and moves it from the PFS to the compute memory of each node. This:

- Helps scaling DDP for data that CANNOT be stored within the memory of one compute unit
- Avoids frequent communications with the PFS

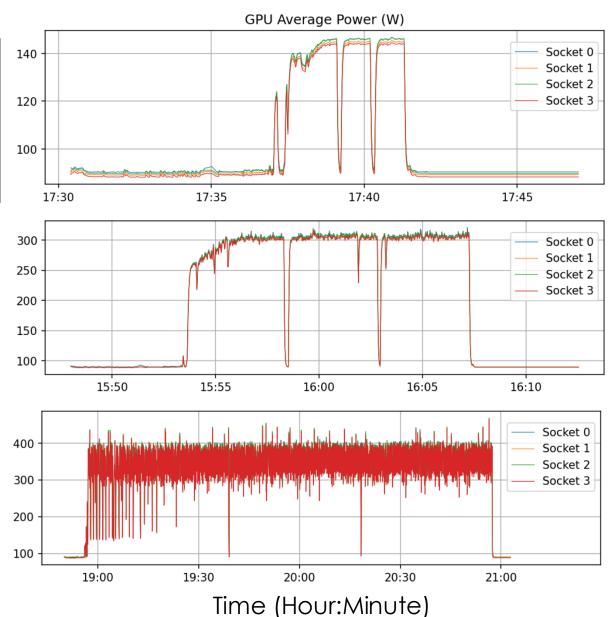


GPU power measurement for models of different size

Model size	SMALL	MEDIUM	LARGE
Type of MPNN layer	EGNN	EGNN	EGNN
# MPNN layers	3	6	6
# neurons in MPNN layers	50	500	2,000
# FC layers	2	2	3
# neurons in FC layers	50	1,000	1,000
Number of parameters	58,404	14,539,004	163,129,004

Top: GNN model sizes used for strong and weak scaling tests on NERSC-Perlmutter and OLCF-Frontier.

Right: GPU Energy use over time for three models – SMALL (top), MEDIUM (middle), and LARGE (bottom). Each line represents one AMD Instinct MI250x.





Synergy between experimental and computational DOE user facilities

Manufacturing Demonstration Facility



Spallation Neutron Source



Center for Nanophase Material Sciences



Experimental data to train Al models

Validation of Al outcomes with experimental data

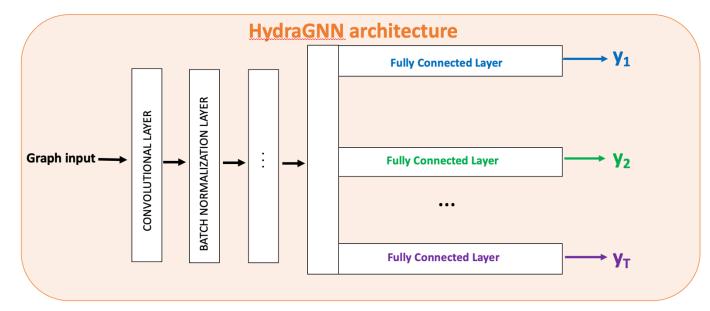


HydraGNN: multi-task learning

Multi-Task Learning stabilizes predictions of multiple properties Each property operates as a mutual regularizer on the other properties

Quantities simultaneously predicted:

- Property y₁
- Property y₂
- •
- Property y_T



 \mathbf{W} = parameters of the neural network to optimize during training

$$\underset{\mathbf{w}}{\operatorname{argmin}} \|\mathbf{y}_{\operatorname{predict},1}(\mathbf{w}) - \mathbf{y}_1\|_2^2 + \|\mathbf{y}_{\operatorname{predict},2}(\mathbf{w}) - \mathbf{y}_2\|_2^2 + \ldots + \|\mathbf{y}_{\operatorname{predict},T}(\mathbf{w}) - \mathbf{y}_T\|_2^2$$

Global Multi-Task Training Loss Function

HydraGNN: equivariance

Equivariance is the property that, under Euclidean transformations, maintains consistency between the geometric structure and the physical properties associated with it. This property is stronger than regular invariance that maintains only geometric properties.

Equivariance collapses the whole class of structurally and functionally equivalent compounds into just one representative.

Implementing equivariance in the message passing layers acts as an **inductive bias**. It eliminates data redundancy and reduces the computational cost to reach the desired accuracy. **This is expected also to reduce energy consumption**.

Examples of invariant material properties:

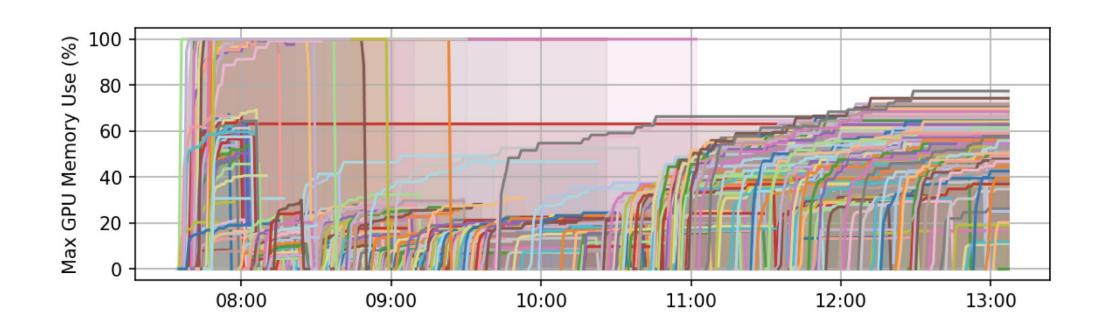
HOMO-LUMO gap, free energy, vibrational spectrum, electronic excitation spectrum

Examples of equivariant material properties:

Electron charge density, atomic forces, magnetic moment



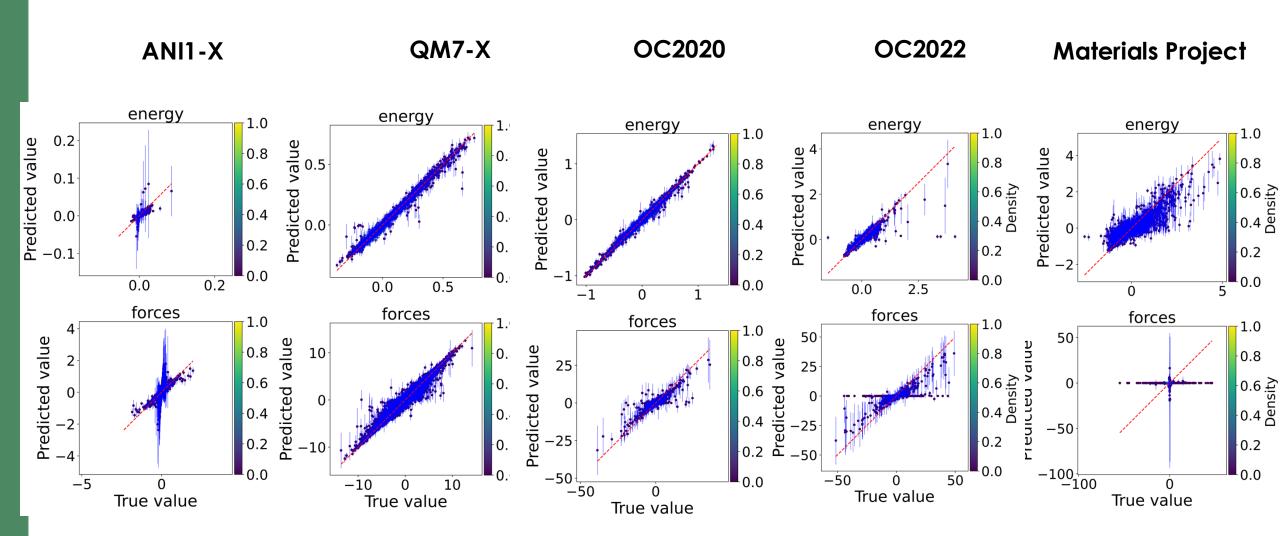
GPU memory utilization and power measurement



Max GPU HBM memory consumption traces sampled via Omnistat telemetry harness during final HPO exercise using 8,560 Frontier nodes (68,480 GCDs) executed on OLCF-Frontier.

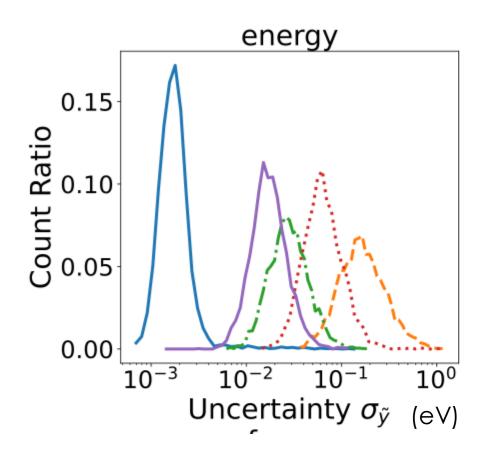


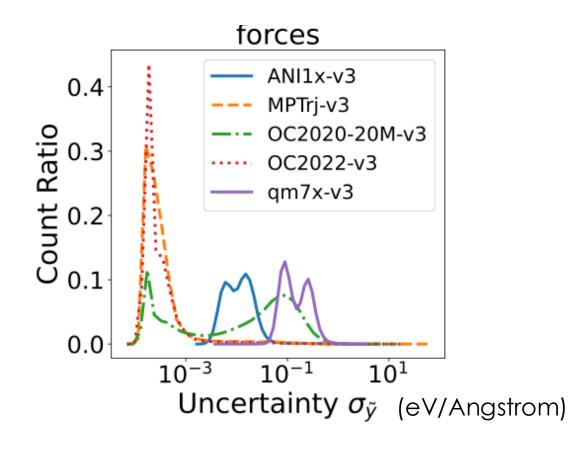
Ensemble uncertainty quantification





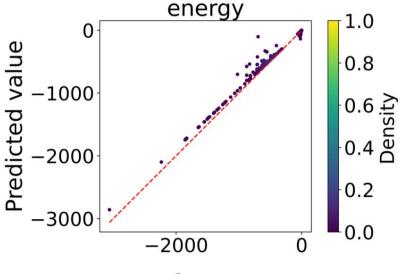
Ensemble Uncertainty Quantification



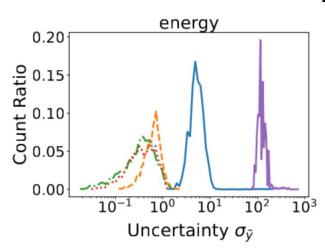


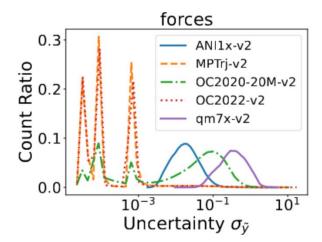
9. Scalable predictive graph foundation models (GFMs)

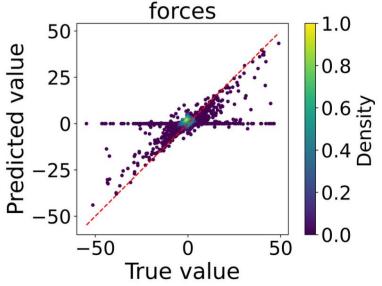
Dataset (Testing portion)	MAE energy (eV)	MAE forces (eV/angstrom)
QM7x	31.91	0.23
ANI1x	1.43	0.02
MPTrj	0.39	0.14
OC2020	0.10	0.11
OC2022	0.15	0.08



Uncertainty quantification









Future Work: Equivariant Generative Diffusion Models with Masking Techniques

<u>Approach</u>: Perform autoregressive graph masking at each iterative step of the reversed diffusion process

- Impose equivariance constraints on the diffusion process to eliminate redundancies
- Use global attention mechanisms with GraphGPS to account for long-range interactions
- Use the mask size as a tunable parameter, to find the best compromise between exploration and exploitation

Standard Masking Original structure INPUT to the GNN Output predicted by the GNN Original structure INPUT to the GNN Output predicted by the GNN Unmasked nodes and edges are subject to perturbation via diffusion

Expected outcome:

- (a) efficient exploration of the material space
- (b) the combined effect of equivariance + the robustness and computational efficiency of autoregressive
 - graph masking will result in **computational and energy savings**

Future Work: Integrate Distributed Data Parallelism (DDP), Model Pipeline Parallelism (MPP), and Model Tensor Parallelism (TMP)

Approach: Hierarchically integrate DDP, MPP, and MTP

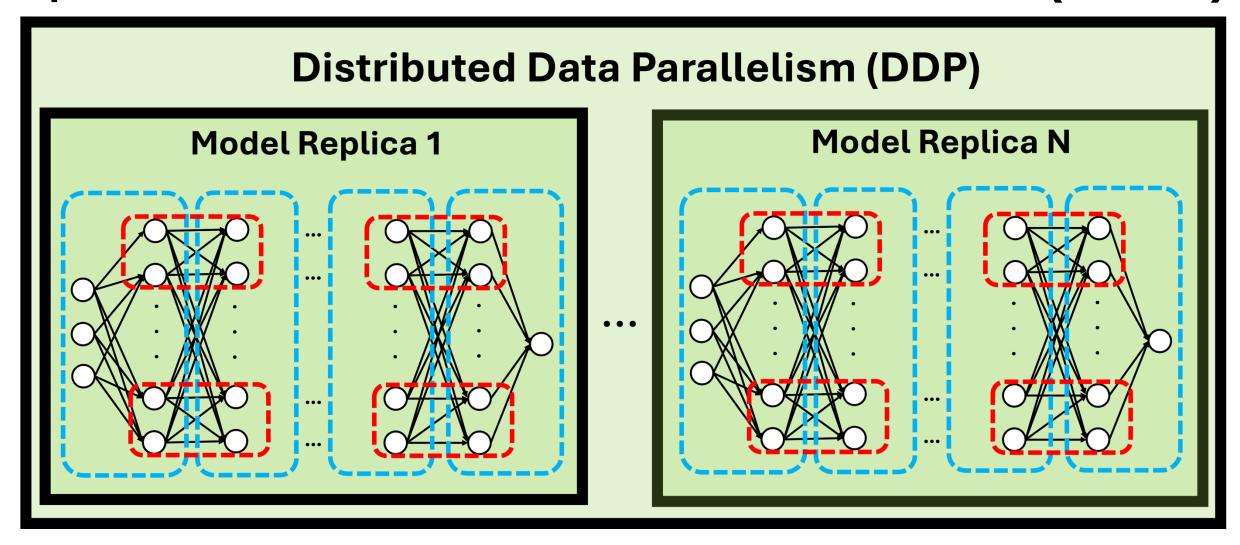
- If the data is too large, DDP will be used to partition the data across multiple GPUs.
- If the data has also broad variability, larger models may be needed to properly capture it. If the number of layers in the model is too large to fit in a single GPU, **MPP** will be used to split different layers across separate GPUs.
- If the number of neurons in each layer makes the model too large to fit in a single GPU, MTP will be
 used to split different neurons across separate GPUs.

Expected outcome:

- GNN architecture that simultaneously combines DDP, MPP, and MTP allowing training of large, complex GNN models
- Optimized latency and memory overhead and efficient training of GNN models at very large scale resulting in energy savings



Future Work: Integrate Distributed Data Parallelism, Model Pipeline Parallelism, and Model Tensor Parallelism (cont.'d)





Future Work: Generalize MTL for Stable and Energy Efficient Data Processing

<u>Approach</u>: Dedicate different heads of the GFM to process data from different sources.

- Ensure compatibility between implementation of hard parameter sharing and 3D parallelization
- New hard parameter sharing implementation:
 - uncovers the correlation between the data in the latent space,
 - sends to the heads only the data that each of them will process.

<u>Expected outcome</u>: Reduced number of parameters and unnecessary calculations, leading to:

- (i) reduced computational resources and energy consumption; and
- (ii) increased numerical stability and resilience against perturbations to the model's parameters

